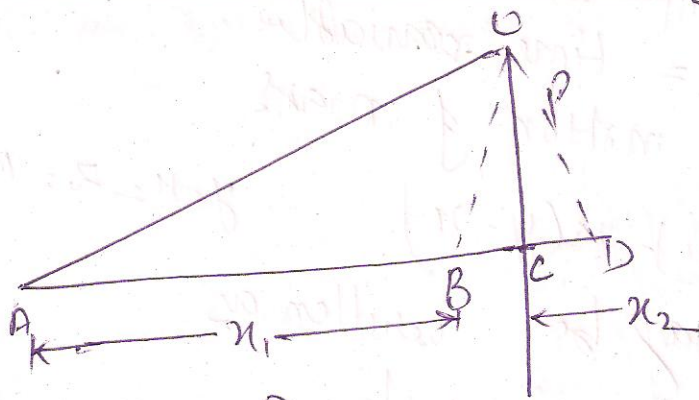
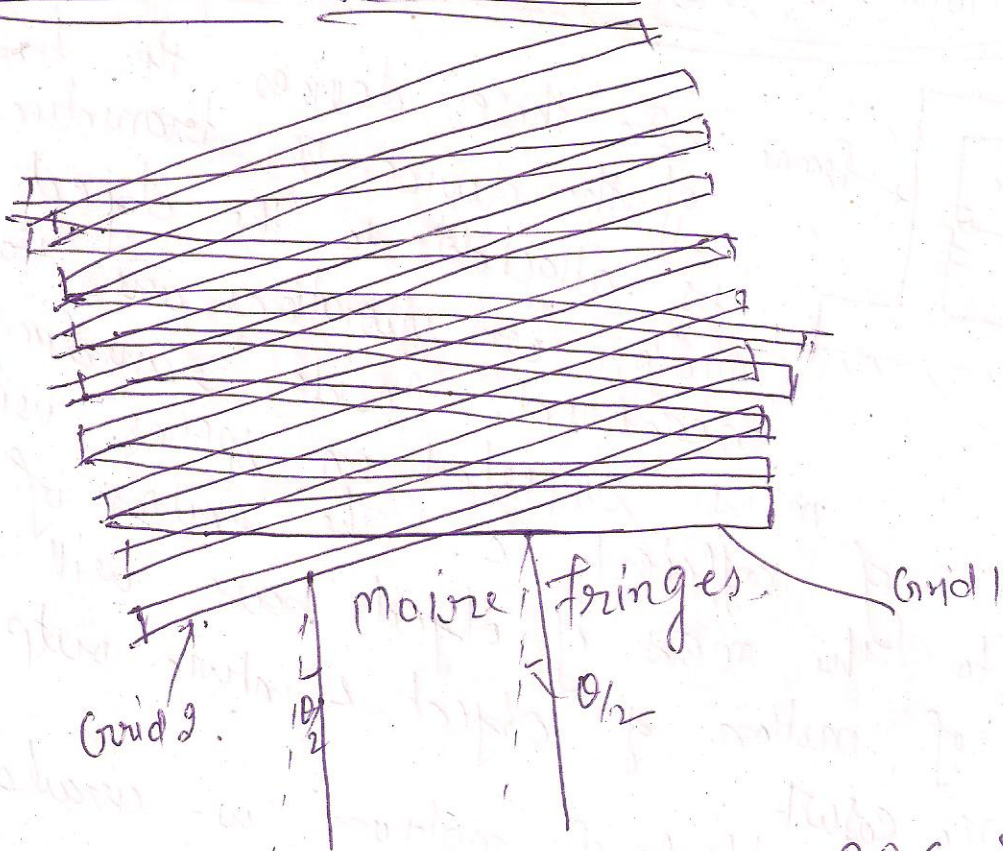


\* Moire Fringe Method :-



$\angle BOC$  &  $\angle COD$  are congruent having three equal angles and one side common

$OB = OD = P$

Grid fringe spacing  $AC = x_1 + x_2$

$$= \frac{OB}{\tan \theta} + OB \cdot \tan \frac{\theta}{2}$$

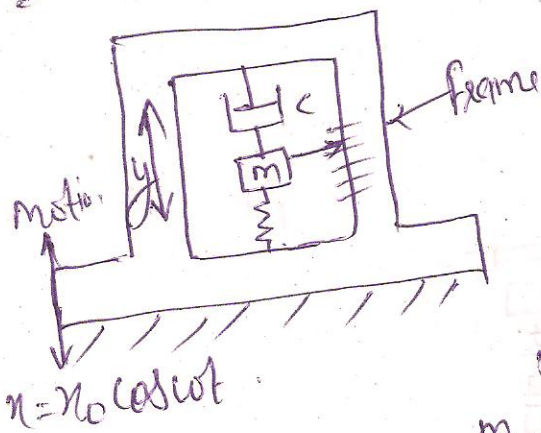
$$= \frac{P}{\tan \theta} + P \cdot \tan \frac{\theta}{2}$$

$$= P \left[ \frac{\cos \theta}{\sin \theta} + \frac{1 - \cos \theta}{\sin \theta} \right]$$

Spacing of fringe =  $\frac{P}{\sin \theta}$

As  $\theta$  is very small  
 $\therefore$  fringe spacing  $\Rightarrow p$ .

\* Absolute motion or vibration devices :-



In these devices the base of the device or transducer is attached to the object whose motion or vibrations are to be measured. Inside transducer a mass  $m$  is supported on spring with damper of coefficient  $c$ . The motion of mass relative to the mass of object base will give indication of motion of object & in turn output also.

Let  $x = x_0 \cos \omega t$   
 where  $x_0 =$  Amplitude of motion,  $\omega =$  circular frequency ( $\omega = 2\pi f$ )  
 $t =$  time variable

$\therefore$  Equation of motion of mass

$$m\ddot{y} = -c(\dot{y} - \dot{x}) - k(y - x)$$

$y - x = z =$  mass relative to frame

The equation may be written as

$$m\ddot{z} + c\dot{z} + kz = m\omega^2 x_0 \cos \omega t$$

For steady state value  
 $z = z_0 \cos(\omega t - \phi)$

$$\text{Amplitude } z_0 = \frac{m\omega^2 x_0}{\sqrt{(k - m\omega^2)^2 + (c\omega)^2}}$$

$$\text{Amplitude Ratio } \frac{z_0}{x_0} = \frac{r^2}{\sqrt{(1 - r^2)^2 + (2\zeta r)^2}}$$